

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Parameterized Complexity of Single Machine Scheduling with Job Time Windows

Maher Mallem¹, Claire Hanen^{2,3}, Alix Munier-Kordon²

¹Inria, CNRS, ENS de Lyon, Université Claude Bernard Lyon 1, LIP, UMR 5668, 69342, Lyon cedex 07, France,

²Sorbonne Université, CNRS, LIP6, F-75005 Paris, France,

³Université Paris Nanterre, F-92000 Nanterre, France,

20 March 2025

Introduction

The Problem
Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition
Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation
Dominance Rule
Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview
Deleting Jobs
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel
Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

Introduction

The Problem
Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition
Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation
Dominance Rule
Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview
Deleting Jobs
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel
Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

Scheduling

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

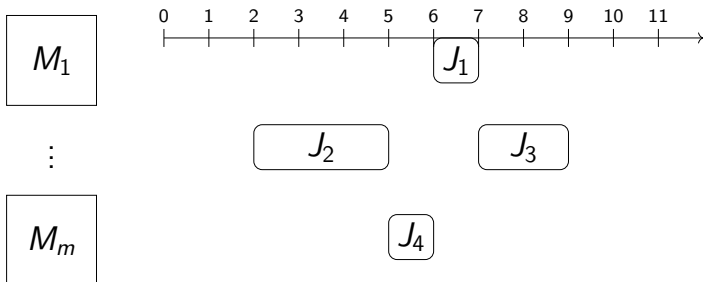
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Scheduling

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

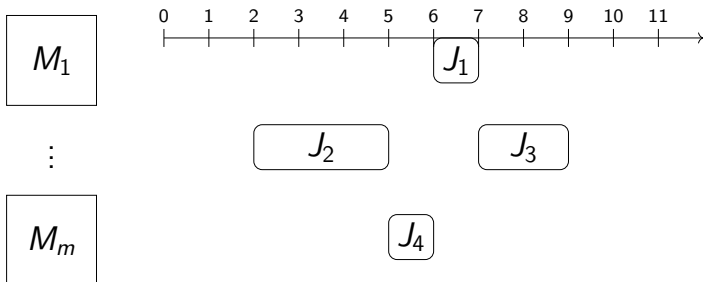
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



machines | job properties | optimization criterion

Scheduling

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

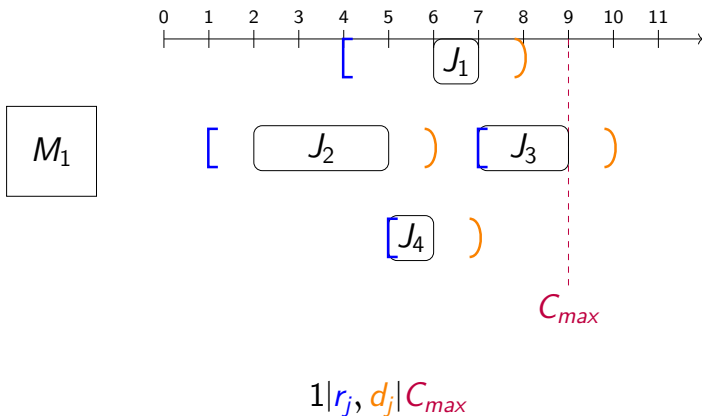
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Scheduling

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

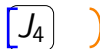
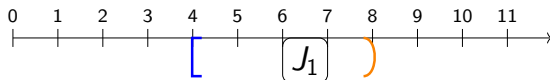
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



$$1|r_j, d_j|\star$$

Scheduling

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

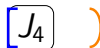
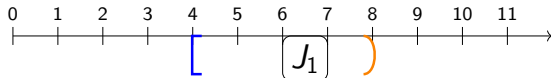
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



$1|r_j, d_j|_\star$ is strongly NP-hard [LRKB 77].

Parameterized complexity classes

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

nondet. $f(k) \cdot \text{poly}(|\mathcal{I}|)$ time

det. $|\mathcal{I}|^{f(k)}$ time

para-NP

XP

XNLP

nondet. $f(k) \cdot \text{poly}(|\mathcal{I}|)$ time
& $f(k) \cdot \log(n)$ space

...

W[2]

W[1]

FPT

det. $f(k) \cdot \text{poly}(|\mathcal{I}|)$ time

Parameterized complexity classes

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

nondet. $f(k) \cdot \text{poly}(|\mathcal{I}|)$ time

det. $|\mathcal{I}|^{f(k)}$ time

$k\text{-COLORING}$

para- NP

XP

$XNLP$

nondet. $f(k) \cdot \text{poly}(|\mathcal{I}|)$ time
& $f(k) \cdot \log(n)$ space

...

$k\text{-DOMINATING SET}$

$W[2]$

$k\text{-CLIQUE}$

$W[1]$

FPT

det. $f(k) \cdot \text{poly}(|\mathcal{I}|)$ time

Parameterized complexity in machine scheduling

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Introduction

The Problem

Parameterized Complexity

- Negative results via *FPT* reductions

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Negative results via *FPT* reductions

- [Bodlaender, Fellows 95] $P|_{prec, p_j = 1} |C_{max}$ is $W[2]$ -hard parameterized by the number m of machines.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Negative results via *FPT* reductions

- [Bodlaender, Fellows 95] $P|_{prec, p_j = 1} C_{max}$ is $W[2]$ -hard parameterized by the number m of machines.

[Mnich, Wiese 15]

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Negative results via *FPT* reductions
 - [Bodlaender, Fellows 95] $P|prec, p_j = 1|C_{max}$ is $W[2]$ -hard parameterized by the number m of machines.
- MIP with a bounded number of integer variables

[Mnich, Wiese 15]

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Negative results via *FPT* reductions
 - [Bodlaender, Fellows 95] $P|prec, p_j = 1|C_{max}$ is $W[2]$ -hard parameterized by the number m of machines.
- MIP with a bounded number of integer variables
 - [Lenstra 83] MILP: [Mnich, Wiese 15]
 - [Dadush et al. 11] MICP
 - [Knop et al. 19] MIMO

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Negative results via *FPT* reductions
 - [Bodlaender, Fellows 95] $P|prec, p_j = 1|C_{max}$ is $W[2]$ -hard parameterized by the number m of machines.
- MIP with a bounded number of integer variables
 - [Lenstra 83] MILP: [Mnich, Wiese 15]
 - [Dadush et al. 11] MICP
 - [Knop et al. 19] MIMO
- Dynamic Programming

Introduction

- The Problem
- Parameterized Complexity

FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

Pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

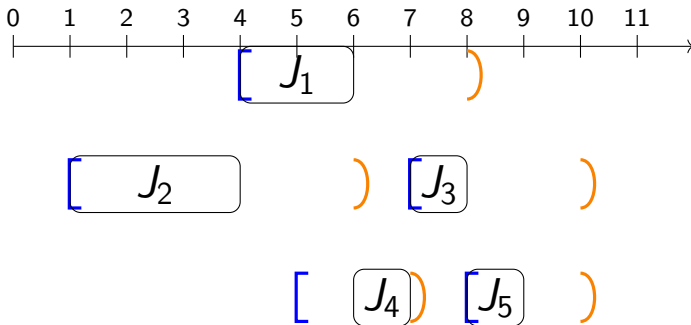
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

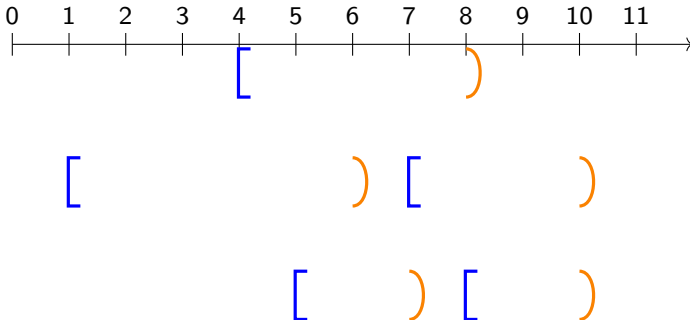
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

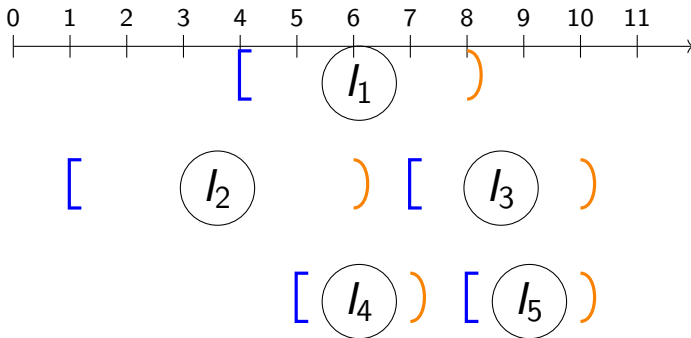
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

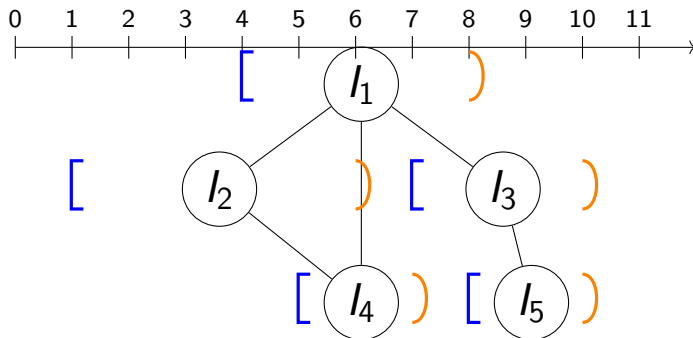
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

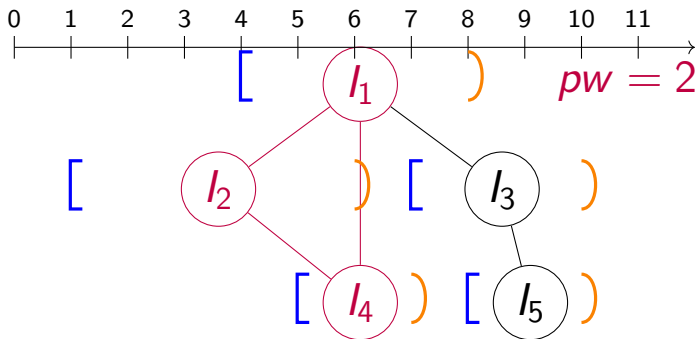
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

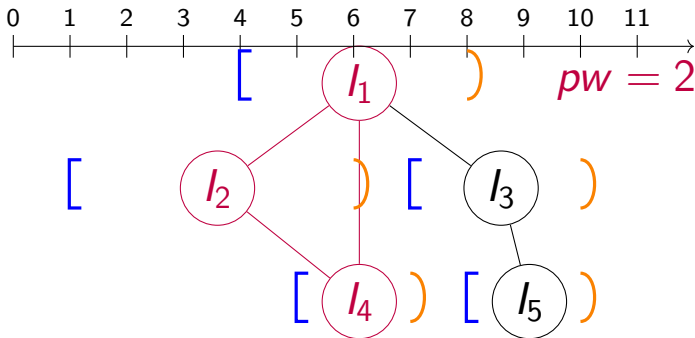
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



[Bodlaender 93] For any interval graph G :

$$\omega(G) = \chi(G) = tw(G) + 1 = pw(G) + 1.$$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

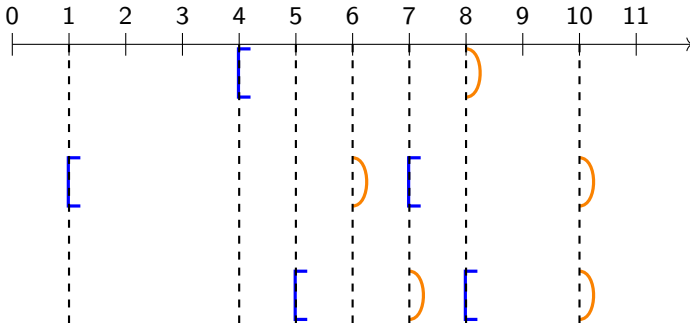
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



[Bodlaender 93] For any interval graph G :

$$\omega(G) = \chi(G) = tw(G) + 1 = pw(G) + 1.$$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

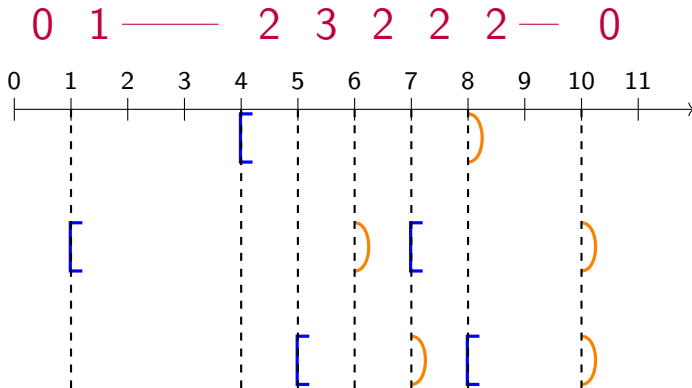
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



[Bodlaender 93] For any interval graph G :

$$\omega(G) = \chi(G) = tw(G) + 1 = pw(G) + 1.$$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

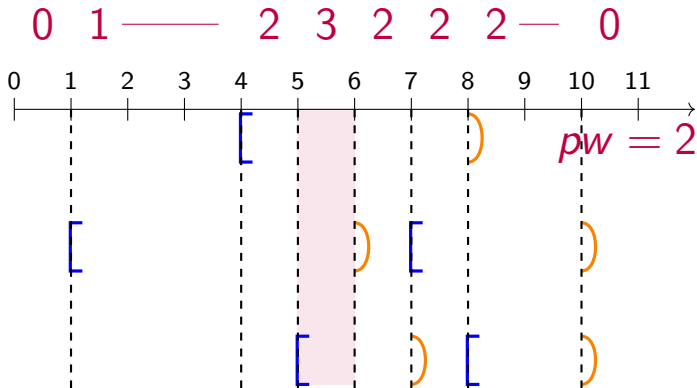
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



[Bodlaender 93] For any interval graph G :

$$\omega(G) = \chi(G) = tw(G) + 1 = pw(G) + 1.$$

Pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

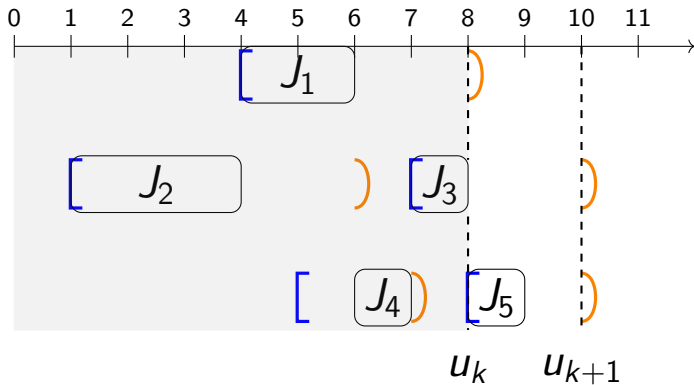
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

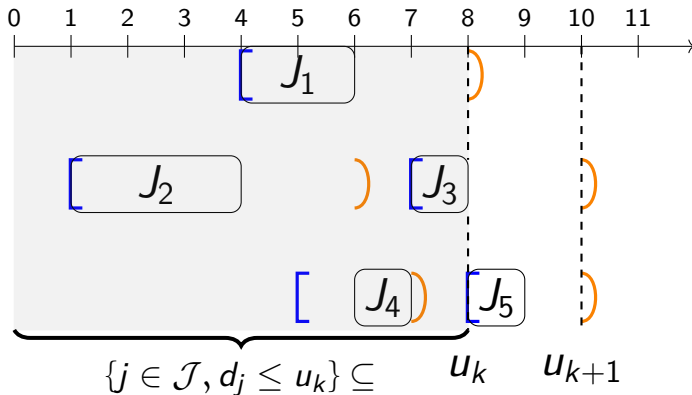
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

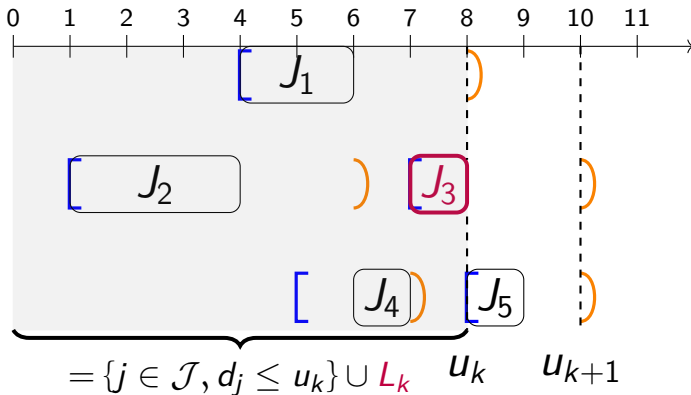
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



- $J_j \in L_k \implies [u_k, u_{k+1}] \subseteq [r_j, d_j]$: at most $pw + 1$ such jobs.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

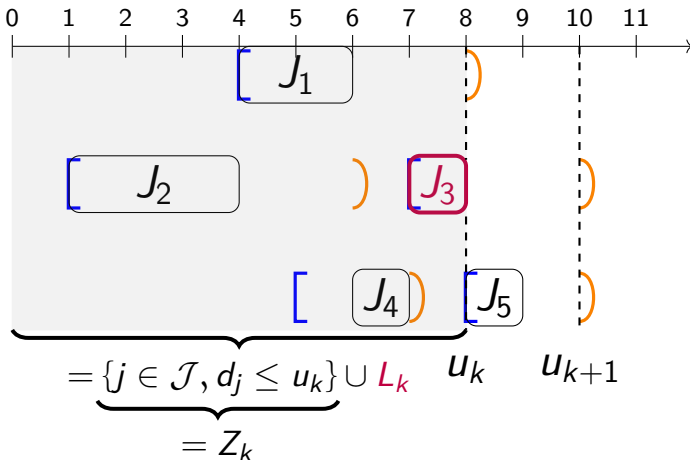
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



- $J_j \in L_k \implies [u_k, u_{k+1}] \subseteq [r_j, d_j]$: at most $pw + 1$ such jobs.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

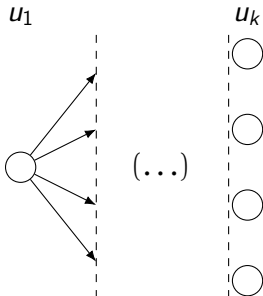
No Polynomial Kernel

Exponential Size Kernels

Conclusion

Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

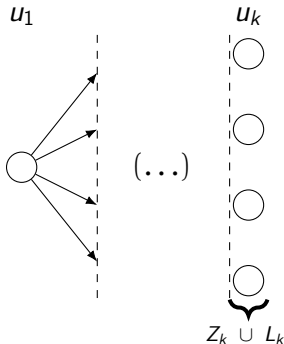
No Polynomial Kernel

Exponential Size Kernels

Conclusion

Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

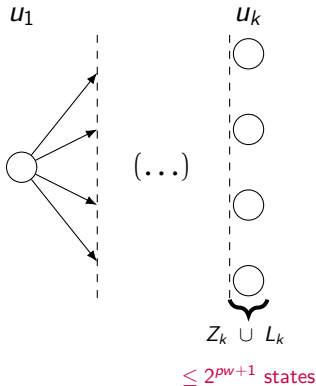
No Polynomial Kernel

Exponential Size Kernels

Conclusion

Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

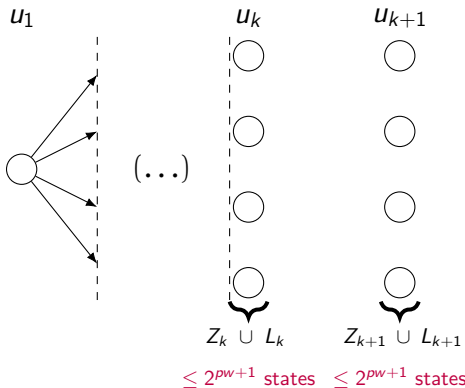
No Polynomial Kernel

Exponential Size Kernels

Conclusion

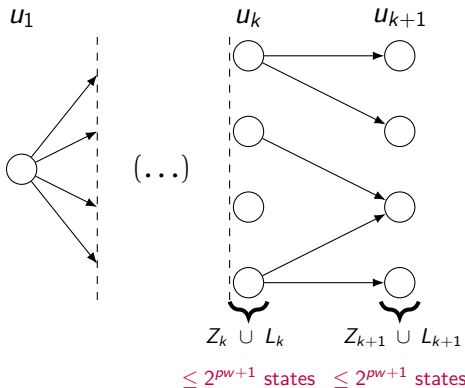
Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.



Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.



Dynamic programming with pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

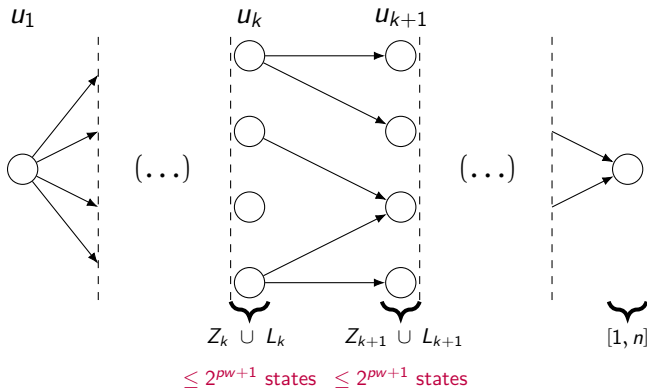
No Polynomial Kernel

Exponential Size Kernels

Conclusion

Dynamic programming state (k, L_k)

- u_k = associated release date/deadline value.
- $Z_k \cup L_k$ = set of jobs starting before u_k .
- State value = minimum makespan among the associated partial schedules.



Algorithm 1: main()

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

▷ Solving $1|r_j, d_j|C_{max}$.

- 1: preprocessing() ▷ Compute sequence $(u_k)_{1 \leq k \leq K}$. Compute associated job subsets.
- 2: $u_{K+1} \leftarrow \infty$
- 3: Create table T with K columns (1 to K) and 2^{pw+1} slots in each column k .
- 4: Initialize T with ∞ everywhere.
- 5: $T[1, \emptyset] \leftarrow 0$
- 6: **for** $k = 1$ to $K - 1$ **do**
- 7: **for each** (L_k, L_{k+1}) **do**
- 8: $T[k + 1, L_{k+1}] \leftarrow \min(T[k + 1, L_{k+1}], \text{extend}(k, L_k, L_{k+1}))$
- 9: **return** $T[K, \emptyset]$

Algorithm 2: $\text{extend}(k, L_k, L_{k+1})$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- 1: $C_{\max} \leftarrow \max(u_k, T[k, L_k])$
- 2: **if** $C_{\max} = \infty$ **then return** ∞
 - ▷ Ensure that all jobs in L_k with a deadline higher than u_{k+1} are still in L_{k+1} .
- 3: **if** $(L_k - Z_{k+1}) \not\subseteq L_{k+1}$ **then return** ∞
 - ▷ Add jobs to the existing partial schedule.
- 4: $\text{mandatory} \leftarrow Z_{k+1} \cap \{J_j \in \mathcal{J}, [u_k, u_{k+1}) \subseteq [r_j, d_j]\}$
- 5: $\text{add} \leftarrow (\text{mandatory} \cup L_{k+1}) - L_k$
- 6: $\text{sort}(\text{add}, \text{nondecreasing } d_j)$
- 7: **for** j in add (in order) **do**
- 8: $C_{\max} \leftarrow C_{\max} + p_j$
- 9: **if** $C_{\max} > d_j$ **then return** ∞
 - ▷ Ensure that all the added jobs start earlier than u_{k+1} .
- 10: $\text{last} \leftarrow \text{last job in add.}$
- 11: **if** $C_{\max} - p_{\text{last}} \geq u_{k+1}$ **then return** ∞
- 12: **return** $C_{\max}$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Mалlem, Hanen, Munier 22]

$1|r_j, d_j|C_{max}$ can be solved in time:

$$\mathcal{O}([(pw + 1) \cdot \log(pw + 1) \cdot 4^{pw}] \cdot n + n^2).$$

Introduction

- The Problem
- Parameterized Complexity

FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

Pathwidth limitation

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

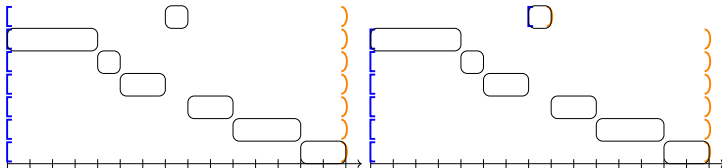
Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Two single machine instances with time windows.



Pathwidth limitation

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

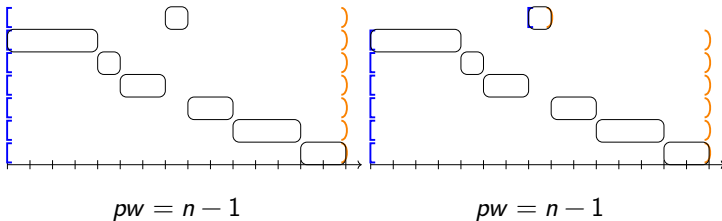
Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Two single machine instances with time windows.



Pathwidth limitation

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

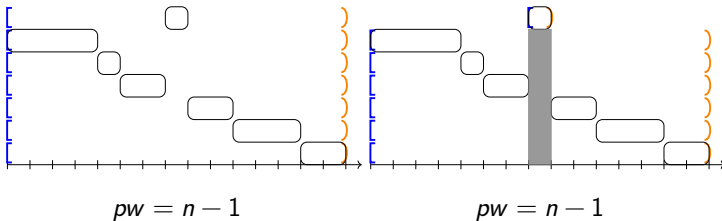
Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Two single machine instances with time windows.



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

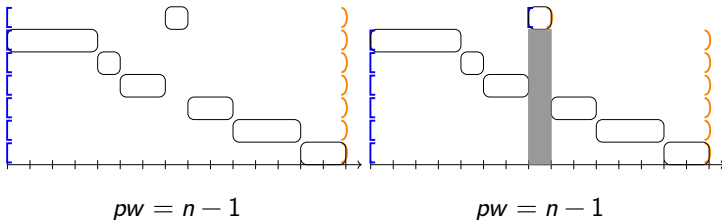
Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Two single machine instances with time windows.



Definition: Proper sets and proper level

- $\forall J_i \in \mathcal{J}, \Pi_i = \{J_j \in \mathcal{J}, r_j < r_i \wedge d_i < d_j\}$
- $q = \max_{J_i \in \mathcal{J}} |\Pi_i|$

Pathwidth limitation

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

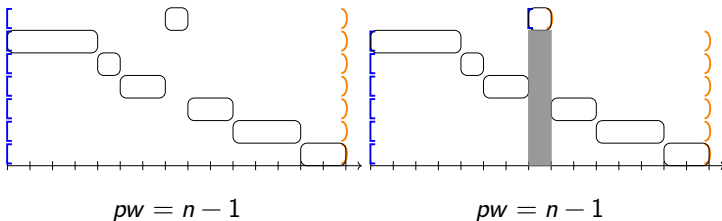
Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Two single machine instances with time windows.



Definition: Proper sets and proper level

- $\forall J_i \in \mathcal{J}, \Pi_i = \{J_j \in \mathcal{J}, r_j < r_i \wedge d_j < d_i\}$ [Erschler, Fontan, Merce 85]
- $q = \max_{J_i \in \mathcal{J}} |\Pi_i|$ [Proskurowski, Telle 99]

Pathwidth limitation

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

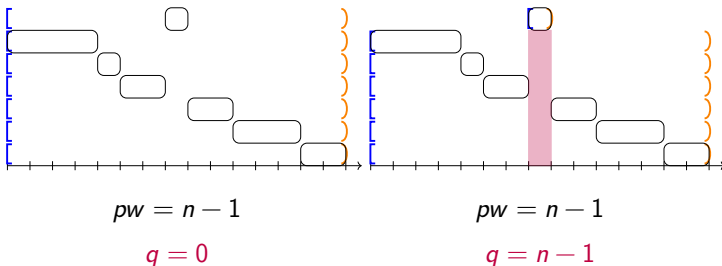
Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- Two single machine instances with time windows.



Definition: Proper sets and proper level

- $\forall J_i \in \mathcal{J}, \Pi_i = \{J_j \in \mathcal{J}, r_j < r_i \wedge d_j < d_i\}$ [Erschler, Fontan, Merce 85]
- $q = \max_{J_i \in \mathcal{J}} |\Pi_i|$ [Proskurowski, Telle 99]

Extending the Earliest Deadline rule

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

- $\prec$ = lexicographic order (non decreasing d_j , non decreasing r_j) on $\mathcal{J}$.
- Renaming the jobs of $\mathcal{J}$ in $[1, n]$.

Definition: Earliest Deadline rule (ED) [Lawler, Moore 69]

Schedule τ follows the (ED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies \tau(i) < \tau(j).$$

Extending the Earliest Deadline rule

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

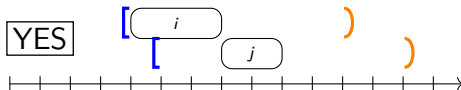
Conclusion

- $\prec$ = lexicographic order (non decreasing d_j , non decreasing r_j) on $\mathcal{J}$.
- Renaming the jobs of $\mathcal{J}$ in $[1, n]$.

Definition: Earliest Deadline rule (ED) [Lawler, Moore 69]

Schedule τ follows the (ED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies \tau(i) < \tau(j).$$



Extending the Earliest Deadline rule

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

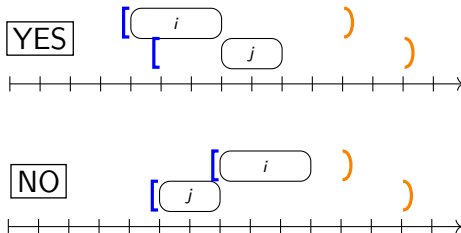
Conclusion

- $\prec$ = lexicographic order (non decreasing d_j , non decreasing r_j) on $\mathcal{J}$.
- Renaming the jobs of $\mathcal{J}$ in $[1, n]$.

Definition: Earliest Deadline rule (ED) [Lawler, Moore 69]

Schedule τ follows the (ED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies \tau(i) < \tau(j).$$



Extending the Earliest Deadline rule (cont.)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Definition: weak Earliest Deadline rule (wED)

Schedule τ follows the (wED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies [\tau(i) < \tau(j)] \vee [j \in \Pi_i] \vee [\exists h \prec i, \tau(j) < \tau(h) < \tau(i)].$$

Extending the Earliest Deadline rule (cont.)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

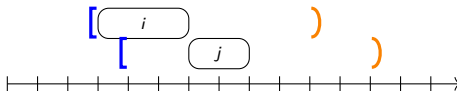
Exponential Size Kernels

Conclusion

Definition: weak Earliest Deadline rule (wED)

Schedule τ follows the (wED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies [\tau(i) < \tau(j)] \vee [j \in \Pi_i] \vee [\exists h \prec i, \tau(j) < \tau(h) < \tau(i)].$$



Extending the Earliest Deadline rule (cont.)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

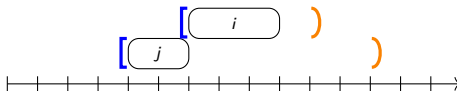
Exponential Size Kernels

Conclusion

Definition: weak Earliest Deadline rule (wED)

Schedule τ follows the (wED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies [\tau(i) < \tau(j)] \vee [j \in \Pi_i] \vee [\exists h \prec i, \tau(j) < \tau(h) < \tau(i)].$$



Extending the Earliest Deadline rule (cont.)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

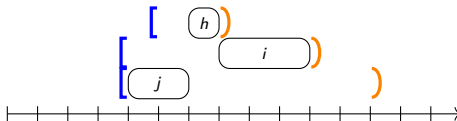
Exponential Size Kernels

Conclusion

Definition: weak Earliest Deadline rule (wED)

Schedule τ follows the (wED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies [\tau(i) < \tau(j)] \vee [j \in \Pi_i] \vee [\exists h \prec i, \tau(j) < \tau(h) < \tau(i)].$$



Extending the Earliest Deadline rule (cont.)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

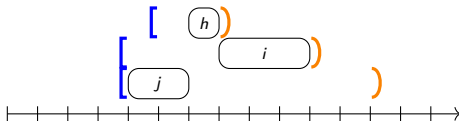
Exponential Size Kernels

Conclusion

Definition: weak Earliest Deadline rule (wED)

Schedule τ follows the (wED) rule if:

$$\forall (i, j) \in \mathcal{J}^2, i \prec j \implies [\tau(i) < \tau(j)] \vee [j \in \Pi_i] \vee [\exists h \prec i, \tau(j) < \tau(h) < \tau(i)].$$



Proposition

On $1|r_j, d_j|C_{max}$ the (wED)-following schedules are dominant.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

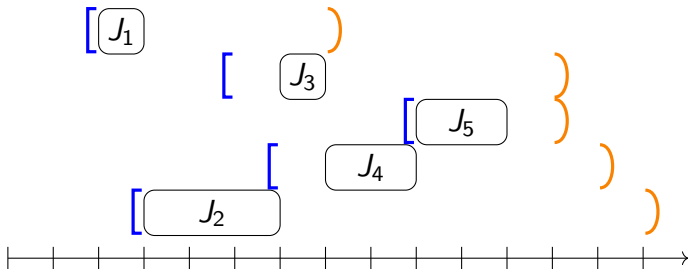
Exponential Size Kernels

Conclusion

Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

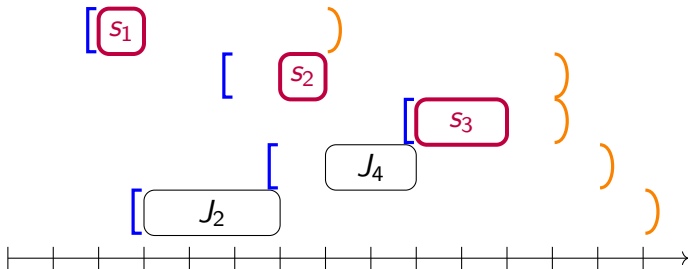
Exponential Size Kernels

Conclusion

Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).

Summit-based schedule enumeration (cont.)

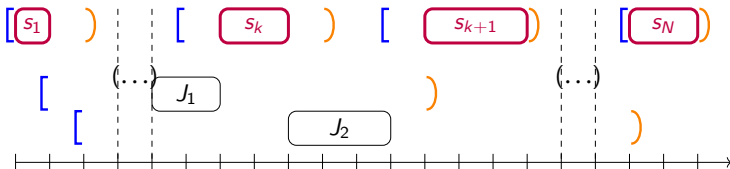
Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).

- Schedule τ follows the (wED) rule

$\Rightarrow \tau$ is of the form $T_1 s_1 \dots s_k T_{k+1} s_{k+1} \dots s_N T_{N+1}$.



Summit-based schedule enumeration (cont.)

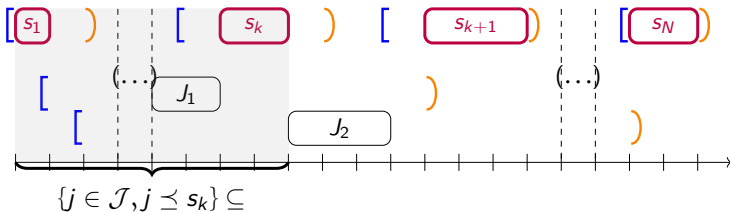
Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).

- Schedule τ follows the (wED) rule

$\Rightarrow \tau$ is of the form $T_1 s_1 \dots s_k T_{k+1} s_{k+1} \dots s_N T_{N+1}$.



Summit-based schedule enumeration (cont.)

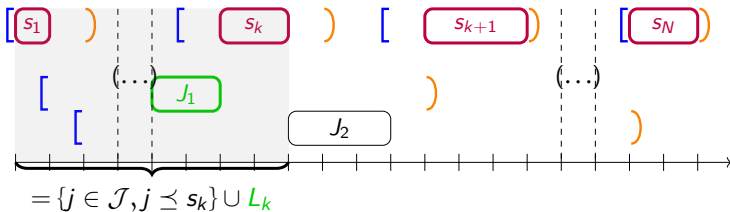
Definition: Summit

A **summit** is a job i in $\mathcal{J}$ such that: $\forall j \in \mathcal{J}, i \notin \Pi_j$.

The summits of the instance are named $s_1 \prec \dots \prec s_N$ ($N \leq n$).

- Schedule τ follows the (wED) rule

$\implies \tau$ is of the form $T_1 s_1 \dots s_k T_{k+1} s_{k+1} \dots s_N T_{N+1}$.



- $j \in L_k \implies j \in \Pi_{s_k}$: at most q such jobs j .

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Mалlem, Hanen, Munier 24]

Single machine scheduling with time windows can be solved in time:

$$\mathcal{O}([(q + 1) \cdot \log(q + 1) \cdot 4^q] \cdot n + n^2).$$

Introduction

- The Problem
- Parameterized Complexity

FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

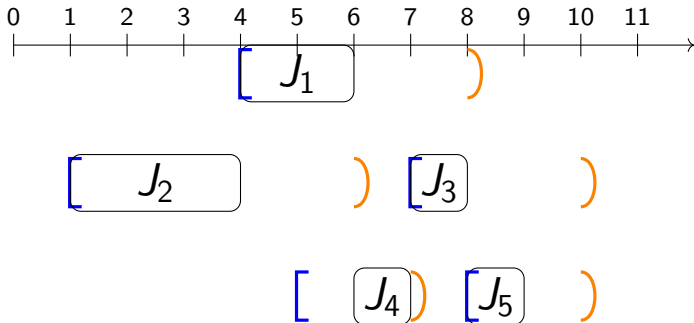
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

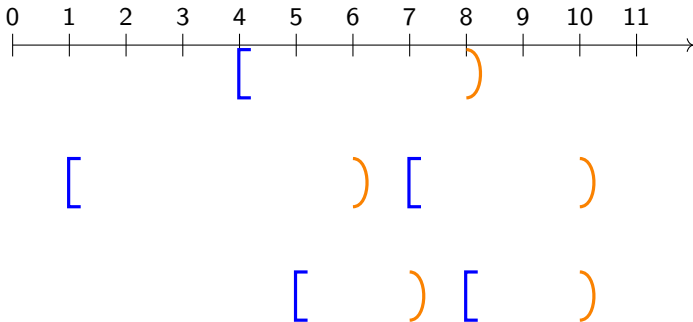
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

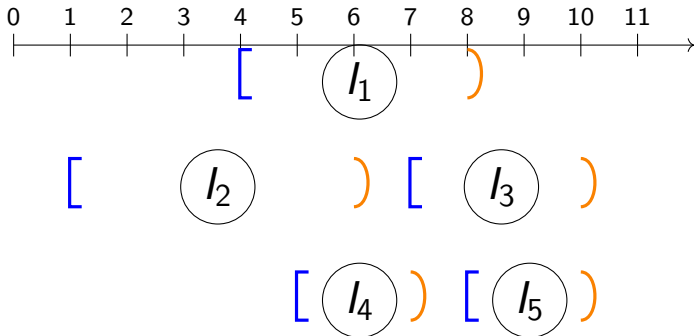
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

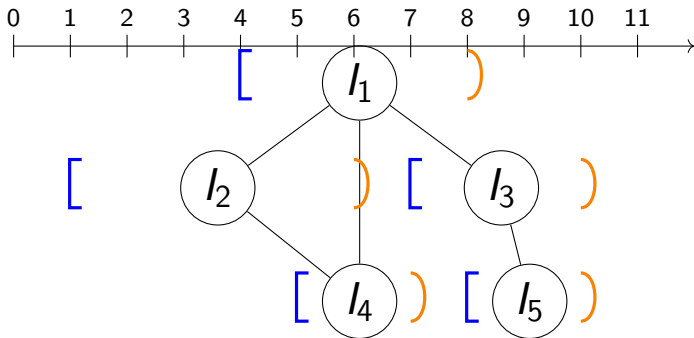
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

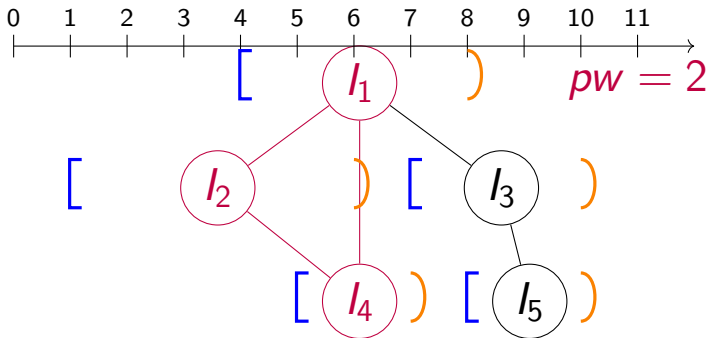
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

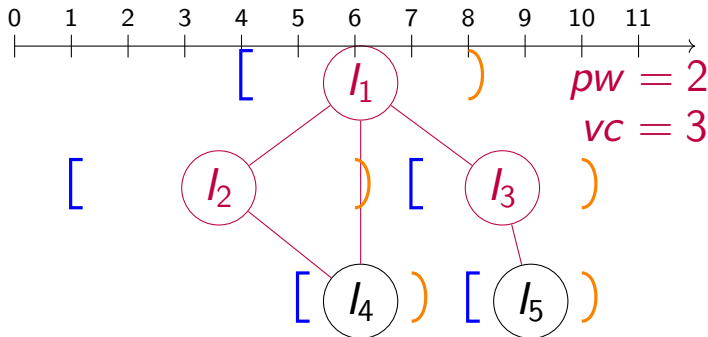
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Pathwidth pw and vertex cover number vc

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

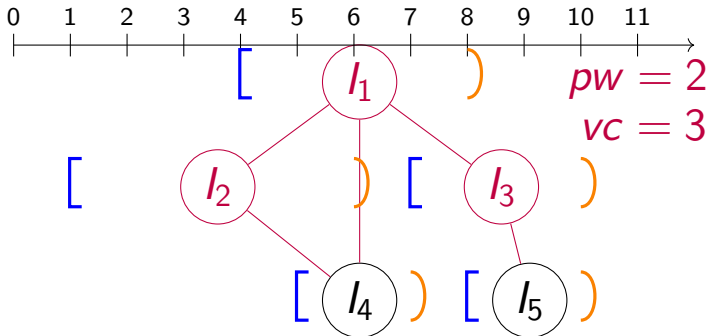
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



Claim

$$pw \leq vc$$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Proposition

$1|r_j, d_j|_\star$ has a polynomial kernel w.r.t. parameter vc .

Polynomial kernel overview

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

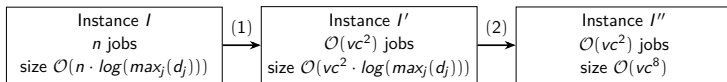
No Polynomial Kernel

Exponential Size Kernels

Conclusion

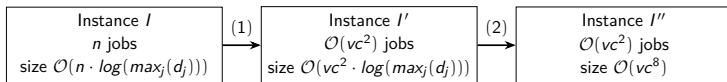
Proposition

$1|r_j, d_j|_\star$ has a polynomial kernel w.r.t. parameter vc .



Proposition

$1|r_j, d_j|_\star$ has a polynomial kernel w.r.t. parameter vc .



- (1) Delete *most* jobs.
 - Use a reduction rule.
 - Time $\mathcal{O}(n^2)$.
- (2) Reduce time values.
 - Translate into a BIP and use a theorem from [Frank, Tardos 87].
 - Time $\mathcal{O}(n^{18})$.

(1) Viewing non-vertex covering jobs as gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

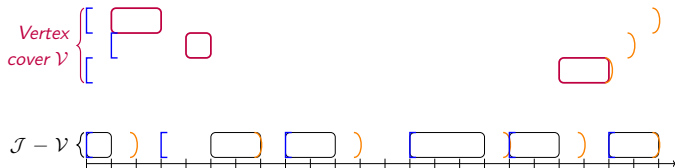
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



(1) Viewing non-vertex covering jobs as gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

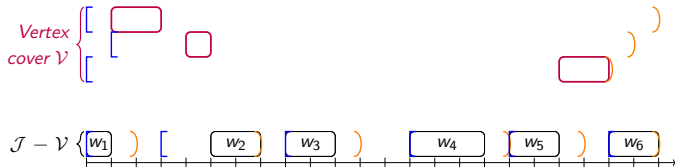
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



- $\mathcal{J} - \mathcal{V}$: jobs $w_1, w_2, \dots, w_{|\mathcal{J} - \mathcal{V}|}$.

(1) Viewing non-vertex covering jobs as gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

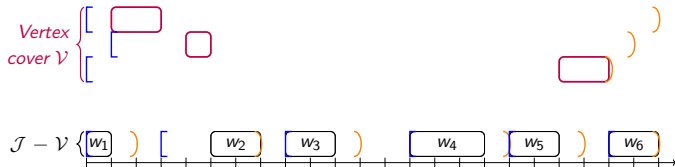
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



- $\mathcal{J} - \mathcal{V}$: jobs $w_1, w_2, \dots, w_{|\mathcal{J} - \mathcal{V}|}$.
- Gap = two consecutive jobs w_i, w_{i+1} .

(1) Viewing non-vertex covering jobs as gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

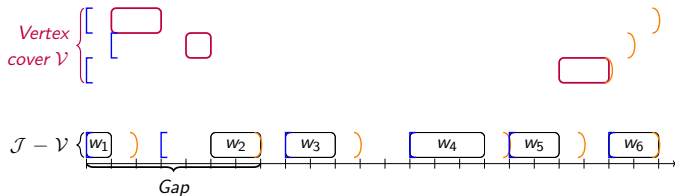
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



- $\mathcal{J} - \mathcal{V}$: jobs $w_1, w_2, \dots, w_{|\mathcal{J} - \mathcal{V}|}$.
- Gap = two consecutive jobs w_i, w_{i+1} .

(1) Viewing non-vertex covering jobs as gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

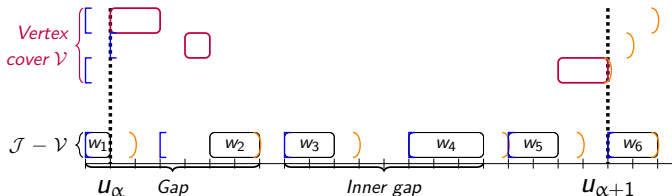
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



- $\mathcal{J} - \mathcal{V}$: jobs $w_1, w_2, \dots, w_{|\mathcal{J} - \mathcal{V}|}$.
- Gap = two consecutive jobs w_i, w_{i+1} .
 - Inner gap: time windows fully included in $[u_\alpha, u_{\alpha+1}]$.

(1) Viewing non-vertex covering jobs as gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

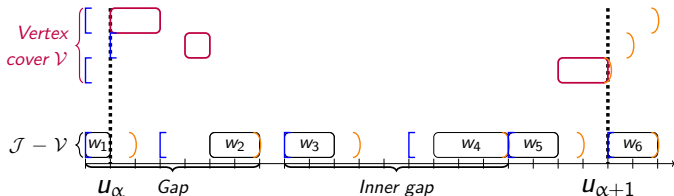
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

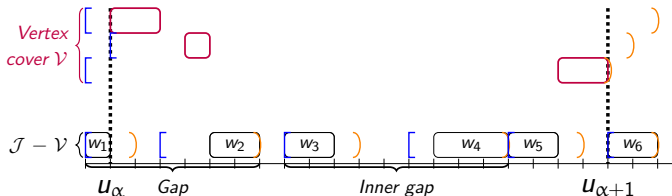
Exponential Size Kernels

Conclusion



- $\mathcal{J} - \mathcal{V}$: jobs $w_1, w_2, \dots, w_{|\mathcal{J}-\mathcal{V}|}$.
- Gap = two consecutive jobs w_i, w_{i+1} .
 - Inner gap: time windows fully included in $[u_\alpha, u_{\alpha+1}]$.
- Maximum capacity: w_i at the earliest, w_{i+1} at the latest.

(1) Viewing non-vertex covering jobs as gaps



- $\mathcal{J} - \mathcal{V}$: jobs $w_1, w_2, \dots, w_{|\mathcal{J}-\mathcal{V}|}$.
- Gap = two consecutive jobs w_i, w_{i+1} .
 - Inner gap: time windows fully included in $[u_\alpha, u_{\alpha+1}]$.
- Maximum capacity: w_i at the earliest, w_{i+1} at the latest.
- $vc_\alpha = |\{J_j \in \mathcal{V}, [u_\alpha, u_{\alpha+1}] \subseteq [r_j, d_j]\}|$.

Reduction rule

In each interval $[u_\alpha, u_{\alpha+1}]$, only keep the $3vc_\alpha$ inner gaps with highest maximum capacity.

(1) Deleting unnecessary inner gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

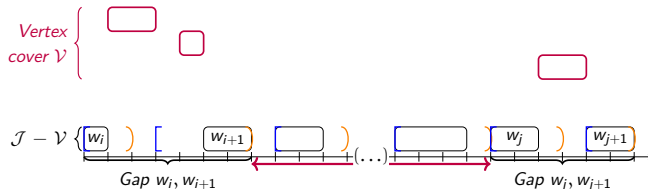
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



(1) Deleting unnecessary inner gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

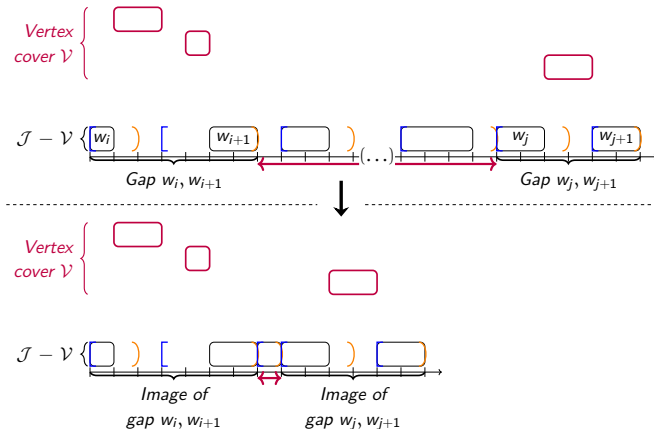
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



(1) Deleting unnecessary inner gaps

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

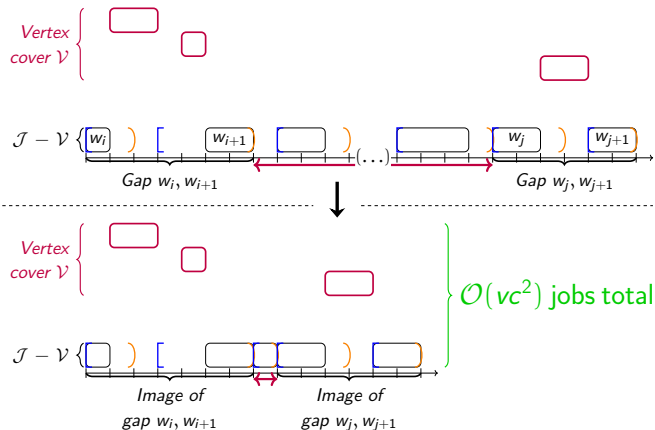
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



(2) Reducing time values

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

(2) Reducing time values

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N - 1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

(2) Reducing time values

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N - 1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

- [Lasserre, Queyranne 92] Binary IP equivalent to $1|r_j, d_j|*$.
 - At most $n + 2$ variables equal to one in each equality of any solution.

(2) Reducing time values

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N - 1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

- [Lasserre, Queyranne 92] Binary IP equivalent to $1|r_j, d_j|*$.
 - At most $n + 2$ variables equal to one in each equality of any solution.
- Use the theorem on instance I' with $\tilde{n} = \mathcal{O}(vc^2)$ jobs.
 - $d = 3\tilde{n}$, $\mathbf{w} = (p_1, r_1, d_1, \dots, p_{\tilde{n}}, r_{\tilde{n}}, d_{\tilde{n}})$, $N = \tilde{n} + 3$.

(2) Reducing time values

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N - 1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

- [Lasserre, Queyranne 92] Binary IP equivalent to $1|r_j, d_j|*$.
 - At most $n + 2$ variables equal to one in each equality of any solution.
- Use the theorem on instance I' with $\tilde{n} = \mathcal{O}(vc^2)$ jobs.
 - $d = 3\tilde{n}$, $\mathbf{w} = (p_1, r_1, d_1, \dots, p_{\tilde{n}}, r_{\tilde{n}}, d_{\tilde{n}})$, $N = \tilde{n} + 3$.
 - Time $\mathcal{O}(vc^{18}) = \mathcal{O}(n^{18})$.
 - Each reduced time value taking space $\mathcal{O}(vc^6)$.

Introduction

- The Problem
- Parameterized Complexity

FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

No polynomial kernel w.r.t. pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Proposition

Unless $NP \subseteq coNP/poly$ there is no polynomial kernel of $1|r_j, d_j|_\star$ w.r.t. pathwidth pw .

No polynomial kernel w.r.t. pathwidth pw

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Proposition

Unless $NP \subseteq coNP/poly$ there is no polynomial kernel of $1|r_j, d_j|^\star$ w.r.t. pathwidth pw .

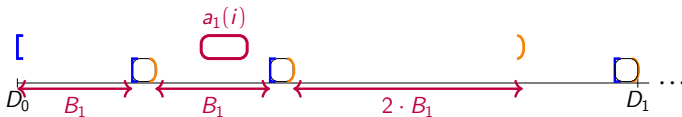
- *Proof:* Cross-composition from PARTITION.
 - $(P_1, \dots, P_t) \mapsto I$
 - $pw \leq poly(\max_i(|P_i|) + \log(t))$

No polynomial kernel w.r.t. pathwidth pw

Proposition

Unless $NP \subseteq coNP/poly$ there is no polynomial kernel of $1|r_j, d_j| \star$ w.r.t. pathwidth pw .

- *Proof:* Cross-composition from PARTITION.
 - $(P_1, \dots, P_t) \mapsto I$
 - $pw \leq poly(\max_i(|P_i|) + \log(t))$

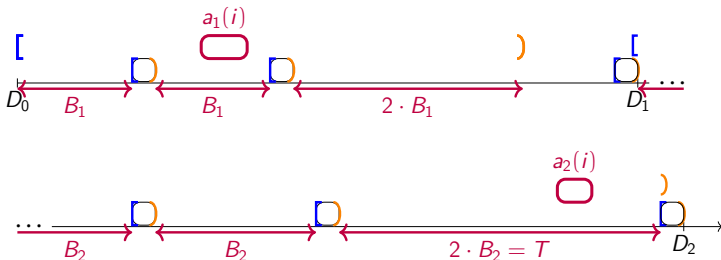


No polynomial kernel w.r.t. pathwidth pw

Proposition

Unless $NP \subseteq coNP/poly$ there is no polynomial kernel of $1|r_j, d_j| \star$ w.r.t. pathwidth pw .

- *Proof:* Cross-composition from PARTITION.
 - $(P_1, \dots, P_t) \mapsto I$
 - $pw \leq poly(\max_i(|P_i|) + \log(t))$

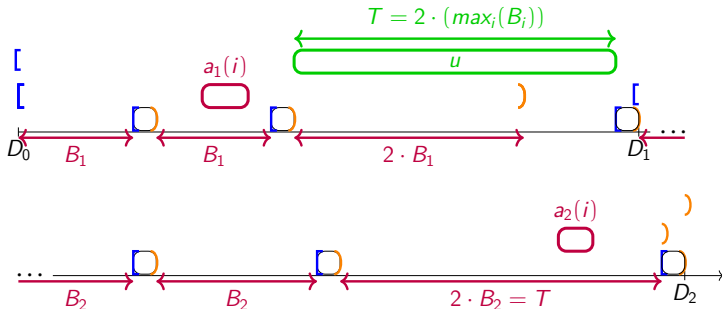


No polynomial kernel w.r.t. pathwidth pw

Proposition

Unless $NP \subseteq coNP/poly$ there is no polynomial kernel of $1|r_j, d_j| \star$ w.r.t. pathwidth pw .

- *Proof:* Cross-composition from PARTITION.
 - $(P_1, \dots, P_t) \mapsto I$
 - $pw \leq poly(\max_i(|P_i|) + \log(t))$



Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Algorithm 1 NaiveKernel($1|r_j, d_j|*$) with pathwidth pw

- 1: Input: an instance $\mathcal{I}$ of $1|r_j, d_j|*$.
- 2: Compute pw in time $\mathcal{O}(n \cdot \log(n))$.
- 3: **if** $|\mathcal{I}| \leq 2^{pw}$ **then**
- 4: **return** $\mathcal{I}$
- 5: **else**
- 6: Use the *FPT* algorithm from [MHMK 22] in time $\mathcal{O}((pw + 1)^2 \cdot 4^{pw} \cdot n + n \cdot \log(n)) = \mathcal{O}(|\mathcal{I}|^2 \cdot \log(|\mathcal{I}|) \cdot n)$.
- 7: **if** the output is YES **then**
- 8: **return** a dummy YES instance of size $\mathcal{O}(1)$.
- 9: **else**
- 10: **return** a dummy NO instance of size $\mathcal{O}(1)$.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Algorithm 1 NaiveKernel($1|r_j, d_j|*$) with pathwidth pw

- 1: Input: an instance $\mathcal{I}$ of $1|r_j, d_j|*$.
- 2: Compute pw in time $\mathcal{O}(n \cdot \log(n))$.
- 3: **if** $|\mathcal{I}| \leq 2^{pw}$ **then**
- 4: **return** $\mathcal{I}$
- 5: **else**
- 6: Use the *FPT* algorithm from [MHMK 22] in time $\mathcal{O}((pw + 1)^2 \cdot 4^{pw} \cdot n + n \cdot \log(n)) = \mathcal{O}(|\mathcal{I}|^2 \cdot \log(|\mathcal{I}|) \cdot n)$.
- 7: **if** the output is YES **then**
- 8: **return** a dummy YES instance of size $\mathcal{O}(1)$.
- 9: **else**
- 10: **return** a dummy NO instance of size $\mathcal{O}(1)$.

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Algorithm 2 $\text{Kernel}(1|r_j, d_j|\star)$ with pathwidth pw

- 1: Input: an instance $\mathcal{I}$ of $1|r_j, d_j|\star$.
- 2: Compute pw and vc in time $\mathcal{O}(n \cdot \log(n))$.
- 3: **if** $vc \leq 2^{pw}$ **then**
- 4: **return** the polynomial kernel of $\mathcal{I}$ w.r.t. vc .
- 5: **else**
- 6: Use the *FPT* algorithm from [MHMK 22] in time $\mathcal{O}((pw + 1)^2 \cdot 4^{pw} \cdot n + n \cdot \log(n)) = \mathcal{O}(vc^2 \cdot \log(vc) \cdot n)$.
- 7: **if** the output is YES **then**
- 8: **return** a dummy YES instance of size $\mathcal{O}(1)$.
- 9: **else**
- 10: **return** a dummy NO instance of size $\mathcal{O}(1)$.

Introduction

- The Problem
- Parameterized Complexity

FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

Conclusion

1 Introduction

- The Problem
- Parameterized Complexity

2 FPT Algorithm with the Pathwidth

- Definition
- Dynamic Programming

3 FPT Algorithm with the Proper Level

- Pathwidth limitation
- Dominance Rule
- Summit-based Decomposition

4 Polynomial Kernel with the Vertex Cover Number

- Overview
- Deleting Jobs
- Reducing Time Values

5 Kernels with the Pathwidth

- No Polynomial Kernel
- Exponential Size Kernels

6 Conclusion

Conclusion

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Parameter	$1 r_j, d_j \star$
q	FPT Kernel of exponential size No polynomial kernel
pw	
vc	FPT Polynomial kernel

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Parameter	$1 r_j, d_j \star$
q	FPT Kernel of exponential size No polynomial kernel
pw	
vc	FPT Polynomial kernel

Future work

- Investigate other scheduling problems with time windows.
 - Postdoc: $1|periodic_L(r_j, d_j)|C_{max}$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Parameter	$1 r_j, d_j *$
q	FPT
pw	Kernel of exponential size No polynomial kernel
vc	FPT Polynomial kernel

Future work

- Investigate other scheduling problems with time windows.
 - Postdoc: $1|\text{periodic}_L(r_j, d_j)|C_{\max}$
- Consider parameters between pathwidth and vertex cover.
 - $pw \rightarrow \text{treedepth} \rightarrow \text{vertex integrity} \rightarrow vc$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Parameter	$1 r_j, d_j \star$
q	FPT Kernel of exponential size No polynomial kernel
pw	
vc	FPT Polynomial kernel

Future work

- Investigate other scheduling problems with time windows.
 - Postdoc: $1|\text{periodic}_L(r_j, d_j)|C_{\max}$
- Consider parameters between pathwidth and vertex cover.
 - $pw \rightarrow \text{treedepth} \rightarrow \text{vertex integrity} \rightarrow vc$
- Improve the existing algorithms.

Parameter hierarchy on $1|r_j, d_j| \star$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

$q \longrightarrow pw \longrightarrow vc$

Parameter hierarchy on $1|r_j, d_j| \star$

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

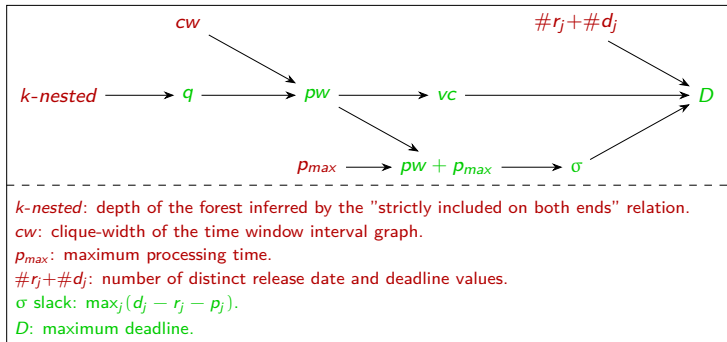
Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion



(2) Reducing time values (with the BIP)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N - 1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

(2) Reducing time values (with the BIP)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N-1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

- [Lasserre, Queyranne 92] Binary IP equivalent to $1|r_j, d_j|*$.

$$BIP(I) : \begin{cases} \text{One job per position} & \sum_{j=1}^n x_{i,j} = 1 \text{ for all } 1 \leq i \leq n. \\ \text{One position per job} & \sum_{i=1}^n x_{i,j} = 1 \text{ for all } 1 \leq j \leq n. \\ \text{Time window checks} & \sum_{j=1}^n r_j \cdot x_{i_1,j} + \sum_{i=i_1}^{i_2} \sum_{j=1}^n p_j \cdot x_{i,j} \leq \sum_{j=1}^n d_j \cdot x_{i_2,j} \\ & \text{for all } 1 \leq i_1 \leq i_2 \leq n. \end{cases}$$

(2) Reducing time values (with the BIP)

Introduction

The Problem

Parameterized Complexity

FPT Algorithm with the Pathwidth

Definition

Dynamic Programming

FPT Algorithm with the Proper Level

Pathwidth limitation

Dominance Rule

Summit-based Decomposition

Polynomial Kernel with the Vertex Cover Number

Overview

Deleting Jobs

Reducing Time Values

Kernels with the Pathwidth

No Polynomial Kernel

Exponential Size Kernels

Conclusion

Theorem [Frank, Tardos 87]

Let $\mathbf{w} = (w_1, \dots, w_d)$ be a vector of rational numbers and let N be a positive integer. Then in time $\mathcal{O}(d^8 \cdot (d + \log(N)))$ one can build a vector $\mathbf{w}' = (w'_1, \dots, w'_d)$ of positive integers such that:

- $w'_i \leq 2^{4d^3} \cdot N^{d(d+2)}$ for all $1 \leq i \leq d$,
- for every $\mathbf{x} = (x_1, \dots, x_d)$ vector of integers such that $\sum_{i=1}^d |x_i| \leq N - 1$:

$$\sum_{i=1}^d w_i x_i \geq 0 \text{ if and only if } \sum_{i=1}^d w'_i x_i \geq 0.$$

- [Lasserre, Queyranne 92] Binary IP equivalent to $1|r_j, d_j|*$.

$$BIP(I) : \begin{cases} \text{One job per position} & \sum_{j=1}^n x_{i,j} = 1 \text{ for all } 1 \leq i \leq n. \\ \text{One position per job} & \sum_{i=1}^n x_{i,j} = 1 \text{ for all } 1 \leq j \leq n. \\ \text{Time window checks} & \sum_{j=1}^n r_j \cdot x_{i_1,j} + \sum_{i=i_1}^{i_2} \sum_{j=1}^n p_j \cdot x_{i,j} \leq \sum_{j=1}^n d_j \cdot x_{i_2,j} \\ & \text{for all } 1 \leq i_1 \leq i_2 \leq n. \end{cases}$$

- Use the theorem on instance I' with $\tilde{n} = \mathcal{O}(vc^2)$ jobs.
 - $d = 3\tilde{n}$, $\mathbf{w} = (p_1, r_1, d_1, \dots, p_{\tilde{n}}, r_{\tilde{n}}, d_{\tilde{n}})$, $N = \tilde{n} + 3$.