

Scheduling

Motivation

Parameterized

Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

Parameterized complexity of parallel machine scheduling with release dates, deadlines and precedence relations

Maher Mallem, Claire Hanen, Alix Munier-Kordon

October 31st 2023



Parallel machine scheduling

Scheduling

Motivation

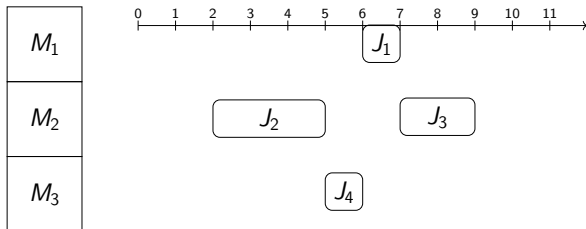
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Parallel machine scheduling

Scheduling

Motivation

Parameterized

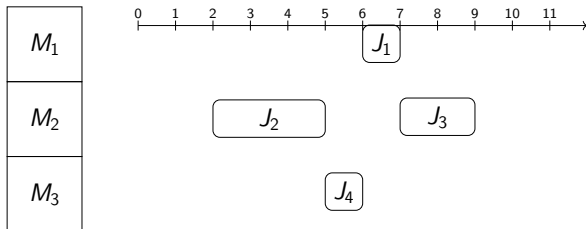
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



machines | job properties | optimization criterion

Parallel machine scheduling

Scheduling

Motivation

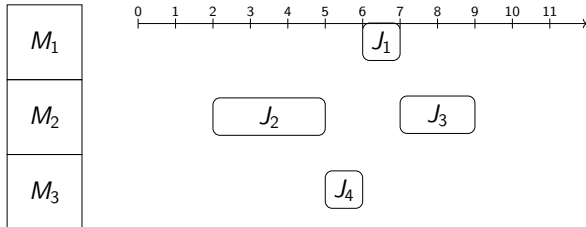
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$P3|.|.$

Parallel machine scheduling

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



1|.|.

Parallel machine scheduling

Scheduling

Motivation

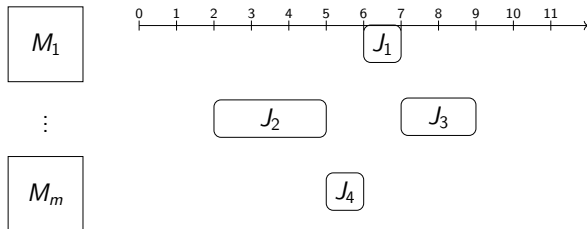
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$P|.|.$

Parallel machine scheduling

Scheduling

Motivation

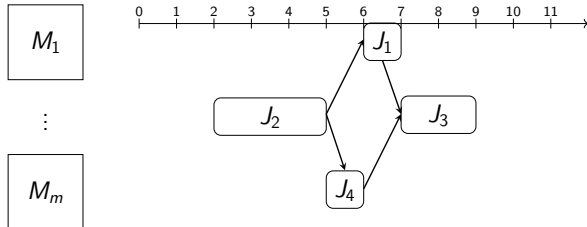
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$P|prec|.$

Parallel machine scheduling

Scheduling

Motivation

Parameterized

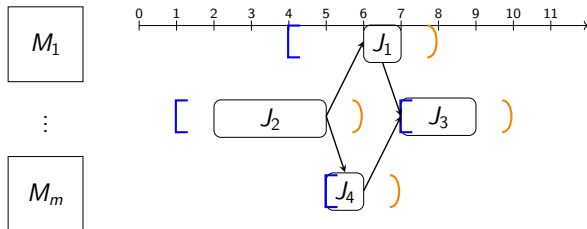
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$$P|prec, r_j, d_j|.$$

Parallel machine scheduling

Scheduling

Motivation

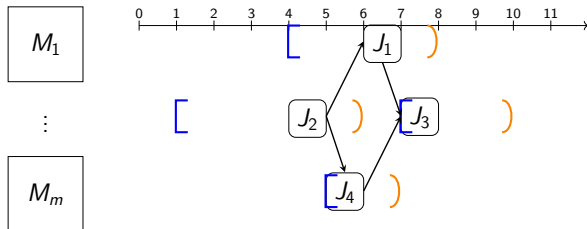
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$$P|prec, p_j = p, r_j, d_j|.$$

Parallel machine scheduling

Scheduling

Motivation

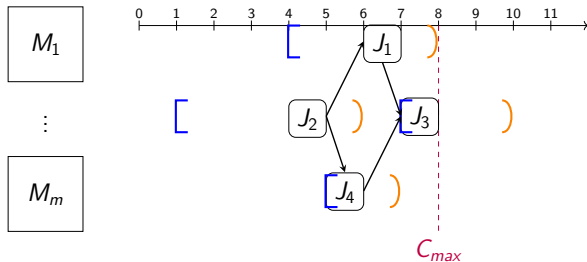
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$$P|prec, p_j = p, r_j, d_j|C_{max}$$

Parallel machine scheduling

Scheduling

Motivation

Parameterized

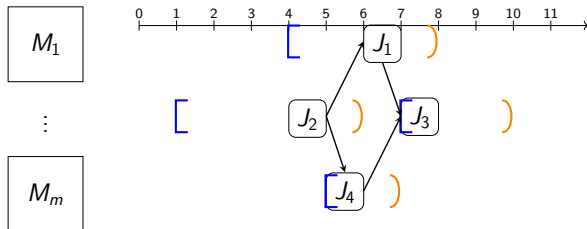
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



$$P|prec, p_j = p, r_j, d_j| \star$$

Typically desired properties

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $1 \rightarrow P$

Typically desired properties

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $1 \rightarrow P$

- $p_j = 1 \rightarrow \text{any } p_j$

Typically desired properties

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $1 \rightarrow P$
- $p_j = 1 \rightarrow \text{any } p_j$
- Add precedence relations *prec*

Typically desired properties

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $1 \rightarrow P$
- $p_j = 1 \rightarrow \text{any } p_j$
- Add precedence relations $prec$
- Add precedence delays $\ell_{i,j}$

Typically desired properties

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $1 \rightarrow P$
- $p_j = 1 \rightarrow \text{any } p_j$
- Add precedence relations $prec$
- Add precedence delays $\ell_{i,j}$

$1|r_j, d_j|*$ is strongly NP-hard. [Brucker, Kan, Lenstra 1977]

Classical complexity theory

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

$$1|p_j = 1, r_j, d_j|*$$

Classical complexity theory

Scheduling

Motivation

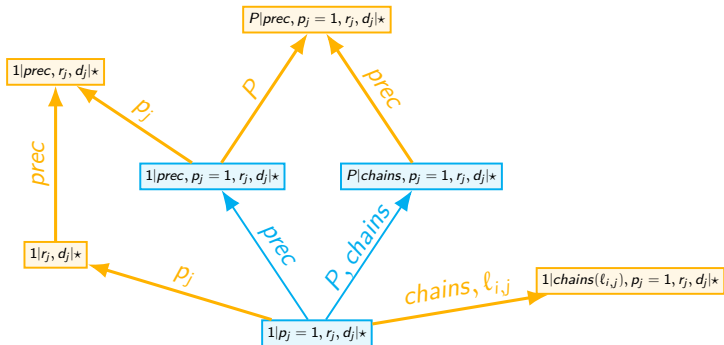
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Going beyond NP-hardness

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $P \subseteq NP$
- P: deterministic time $poly(n)$
- NP: nondeterministic time $poly(n)$

Going beyond NP-hardness

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $P \subseteq NP$
 - $FPT \subseteq \text{para-NP}$, parameter k
- P : deterministic time $\text{poly}(n)$
 - FPT : deterministic time $f(k) \times \text{poly}(n)$
- NP : nondeterministic time $\text{poly}(n)$
 - para-NP : nondeterministic time $f(k) \times \text{poly}(n)$

Going beyond NP-hardness

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- $P \subseteq NP$
 - $FPT \subseteq \text{para-NP}$, parameter k
- P : deterministic time $poly(n)$
 - FPT : deterministic time $f(k) \times poly(n)$
- NP : nondeterministic time $poly(n)$
 - para-NP : nondeterministic time $f(k) \times poly(n)$
- $FPT \subseteq W[1] \subseteq W[2] \subseteq \dots \subseteq \text{para-NP}$.
 - $W[1] - \text{hard} = \text{"unlikely to be FPT"}$.

Parameterized complexity in machine scheduling

Scheduling

Motivation

Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- [Bodlaender, Fellows 1995]
 - #machines m : $P|prec, p_j = 1|C_{max}$ is $W[2]$ -hard.

Parameterized complexity in machine scheduling

Scheduling

Motivation

Parameterized Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- [Bodlaender, Fellows 1995]
 - #machines m : $P|prec, p_j = 1|C_{max}$ is $W[2]$ -hard.
- [Mnich, Wiese 2015]
 - Maximum processing time p_{max} : $P||C_{max} \in FPT$.

Parameterized complexity in machine scheduling

Scheduling

Motivation

Parameterized

Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion

- [Bodlaender, Fellows 1995]
 - #machines m : $P|_{prec, p_j = 1}|C_{max}$ is $W[2]$ -hard.
- [Mnich, Wiese 2015]
 - Maximum processing time p_{max} : $P||C_{max} \in FPT$.
- [Hermelin, Karhi, Pinedo, Shabtay 2018]
 - #distinct d_j , #distinct p_j , #distinct w_j : $1||\sum w_j U_j \in FPT$ with two of the three.

Pathwidth pw

Scheduling

Motivation

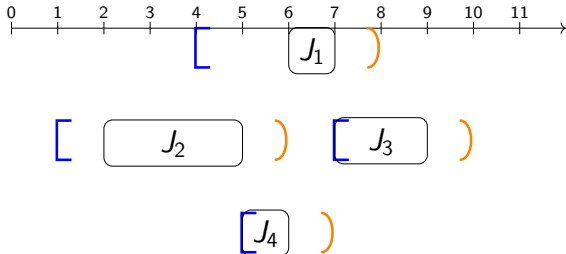
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Pathwidth pw

Scheduling

Motivation

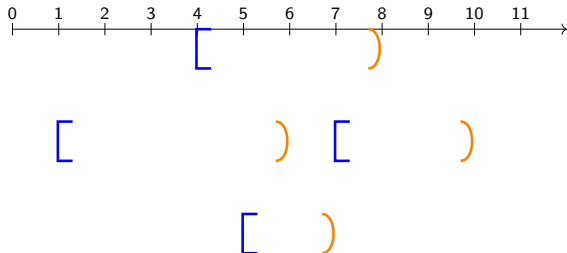
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Pathwidth pw

Scheduling

Motivation

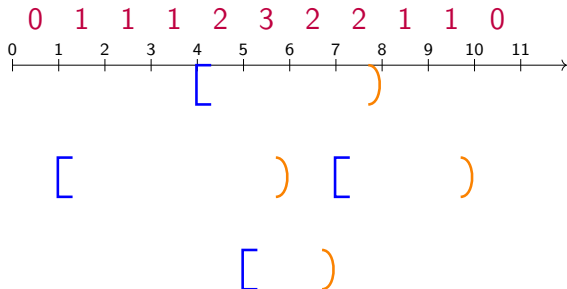
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Pathwidth pw

Scheduling

Motivation

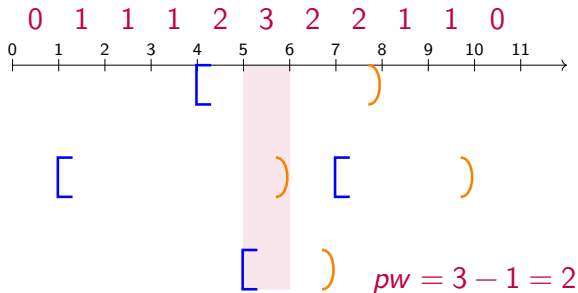
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Pathwidth pw

Scheduling

Motivation

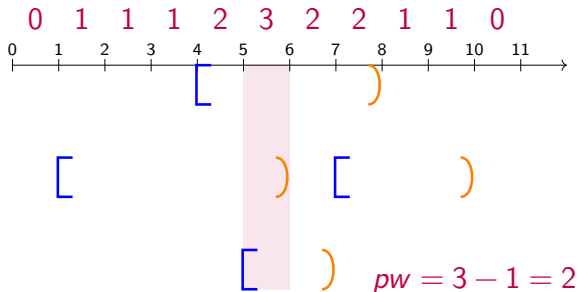
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



- [Munier 2021] $P|prec, p_j = 1, r_j|L_{max}$ is FPT parameterized by pw .

Parameter p_w

Scheduling

Motivation

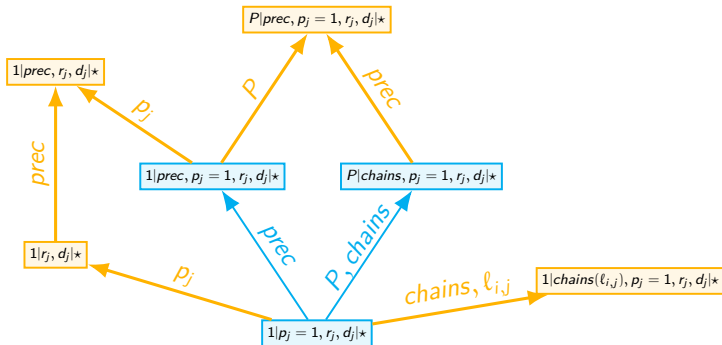
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Parameter p_w

Scheduling

Motivation

Parameterized

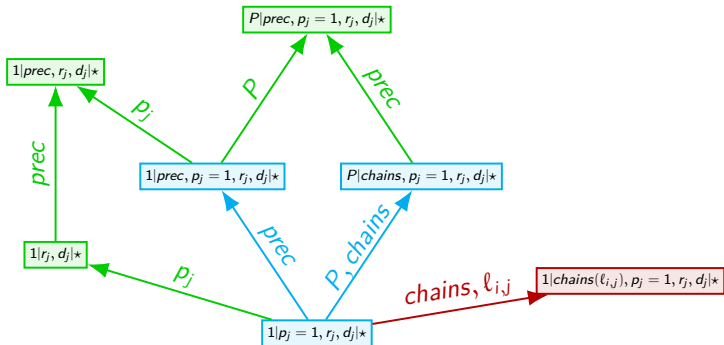
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Parameter p_w

Scheduling

Motivation

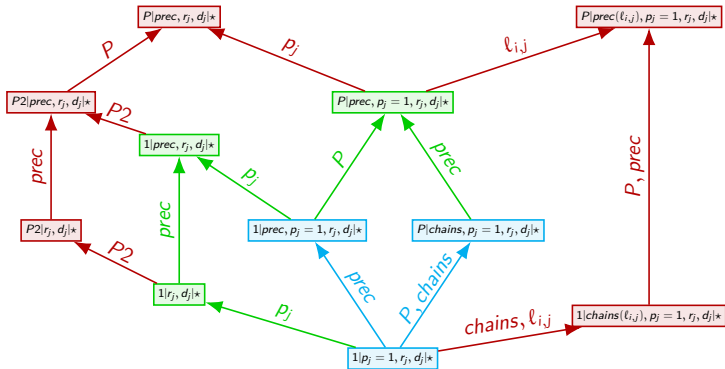
Parameterized
Complexity

General

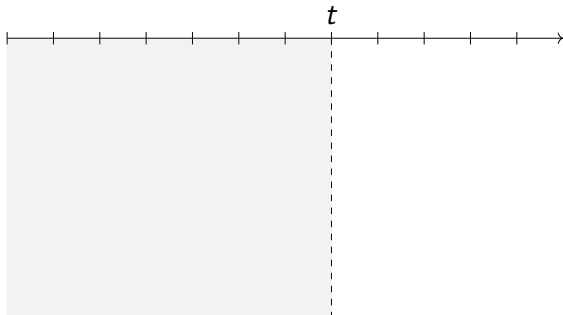
Pathwidth

Pathwidth & maximum delay

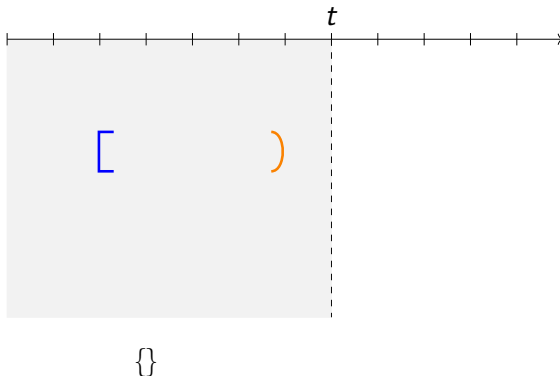
Conclusion



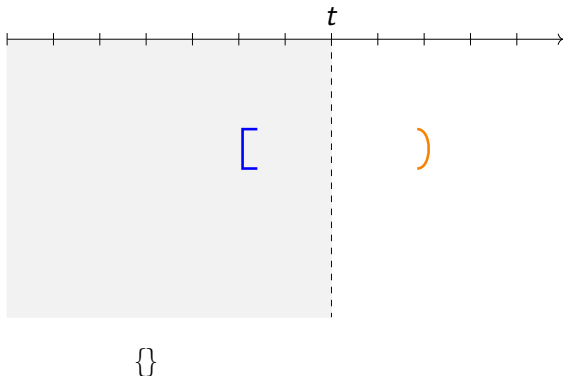
- Dynamic programming algorithm on active schedules



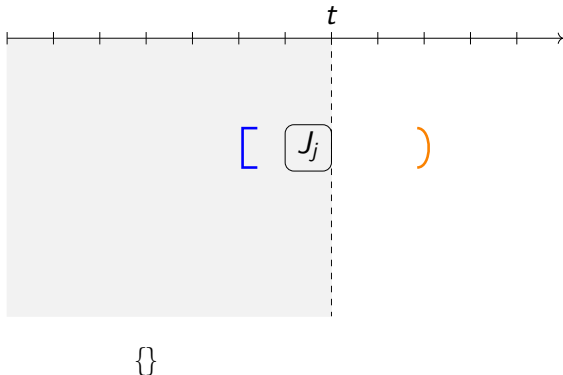
- Dynamic programming algorithm on active schedules



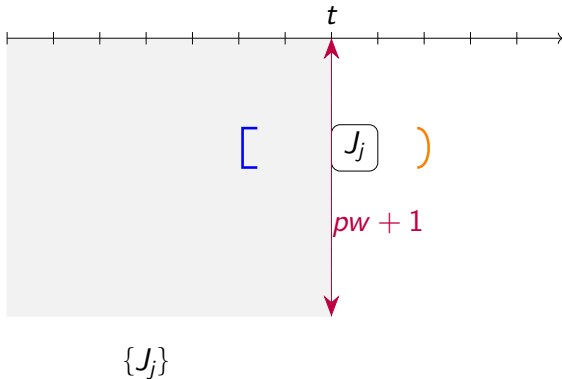
- Dynamic programming algorithm on active schedules



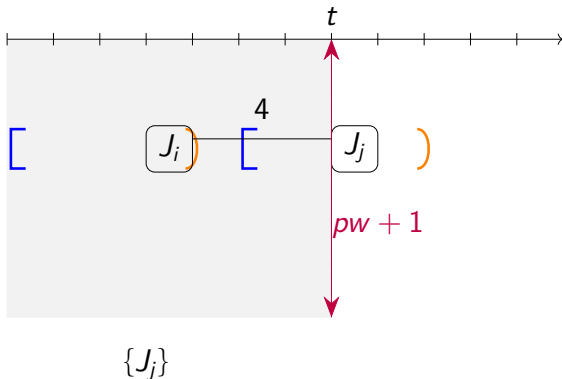
- Dynamic programming algorithm on active schedules



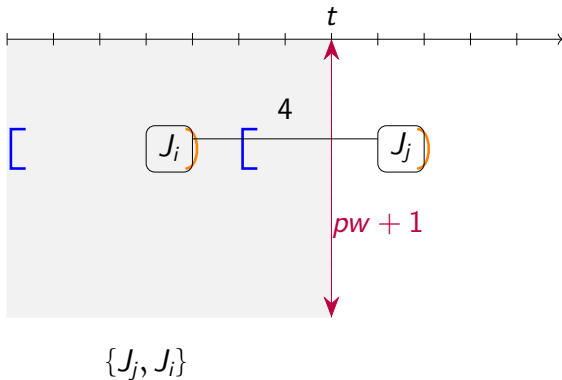
- Dynamic programming algorithm on active schedules



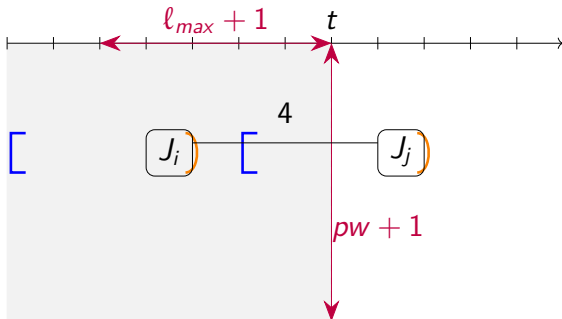
- Dynamic programming algorithm on active schedules



- Dynamic programming algorithm on active schedules



- Dynamic programming algorithm on active schedules



$$|\{J_j, J_i\}| = \mathcal{O}(pw \times \ell_{max})$$

Parameter $pw + \ell_{max}$

Scheduling

Motivation

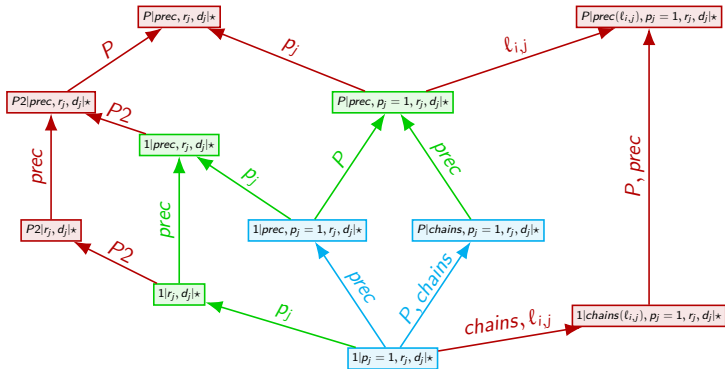
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Parameter $pw + \ell_{max}$

Scheduling

Motivation

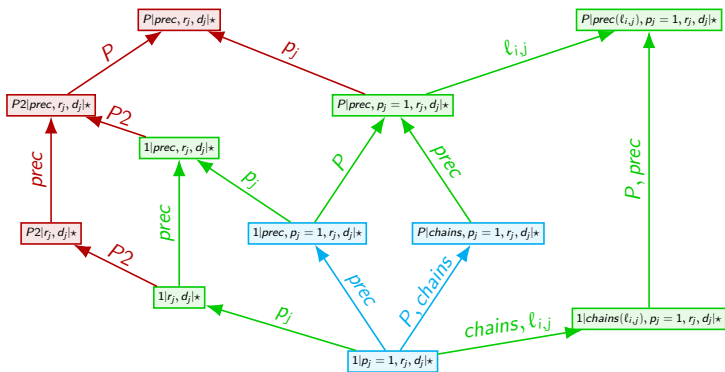
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



Parameter $pw + \ell_{max}$

Scheduling

Motivation

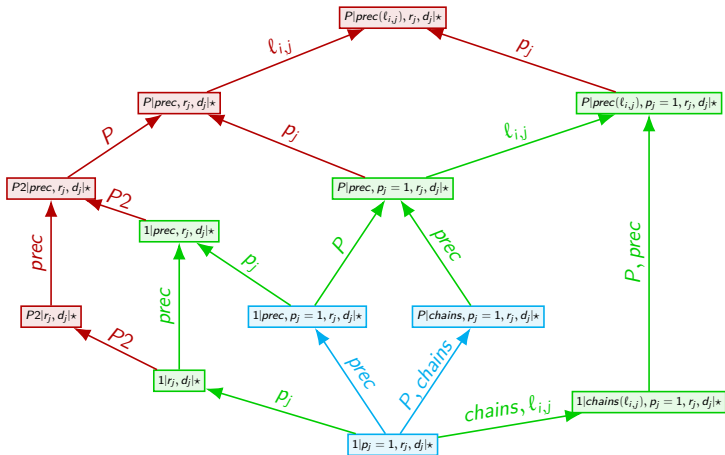
Parameterized
Complexity

General

Pathwidth

Pathwidth & maximum delay

Conclusion



- In-depth classification of scheduling problems (beyond P vs NP).
- More instance families with efficient exact methods.
- [Scheduling Zoo](#) [Dürr et al. 2006-Present]