

FPT vs para-NP

Related work

Examples of parameters

Pathwidth

Problem definition

Hardness reduction

EXACT DELAYS, pathwidth 1

MIN DELAYS, pathwidth 2

MIN DELAYS, pathwidth 1

Conclusion

Parameterized complexity of a single machine scheduling problem

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- $P \subseteq NP$
 - P: deterministic time $poly(n)$
 - NP: nondeterministic time $poly(n)$
- $FPT \subseteq \text{para-NP}$, parameter k
 - FPT: deterministic time $f(k) \times poly(n)$
 - para-NP: nondeterministic time $f(k) \times poly(n)$
- $P = NP$ iff $\exists k$, $FPT = \text{para-NP}$ [Flum, Grohe 1998]

The W-hierarchy

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- $\text{FPT} \subseteq \text{W}[1] \subseteq \text{W}[2] \subseteq \dots \subseteq \text{para-NP}$
 - $\text{W}[1]$ -complete: INDEPENDENT SET, CLIQUE
 - $\text{W}[2]$ -complete: DOMINATING SET

A few examples in scheduling

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- [Bodlaender, Fellows 1995]
 - #machines: $P|_{prec}, p_j = 1|C_{max}$ W[2]-hard
- [Mniech, Wiese 2015]
 - Maximum processing time p_{max} : $P||C_{max} \in \text{FPT}$
- [Hermelin, Karhi, Pinedo, Shabtay 2018]
 - #distinct d_j , #distinct p_j , #distinct w_j : $1||\sum w_j U_j \in \text{FPT}$ with two of the three

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Definition: pathwidth

$$\mu \stackrel{\text{def}}{=} \max_{0 \leq t < \max_j d_j} |\{j \mid r_j \leq t < d_j\}| - 1$$

Recent work:

- $1|r_j, s_{jk}, \text{reject}, \tilde{d}_j| \sum_{j \notin R} v_j - \sum_{j \notin R} w_j T_j \in \text{FPT} (\mu + \text{slack})$ [de Weerd et al. 2020]
- $P|prec, p_j = 1, r_j|L_{\max} \in \text{FPT} (\mu)$ [Munier-Kordon, Tang 2021]
- $P|M_j(\text{type}), prec, r_j|L_{\max} \in \text{FPT} (\mu + p_{\max})$ [Hanan, Munier-Kordon 2022]

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- Decision problem: $1|chains(l_{i,j}), p_j = 1, r_j, d_j|*$
- Two cases:
 - EXACT DELAYS: $J_i \prec J_j \implies \sigma(j) = \sigma(i) + 1 + l_{i,j}$
 - MIN DELAYS: $J_i \prec J_j \implies \sigma(j) \geq \sigma(i) + 1 + l_{i,j}$
- Goal: prove para-NP-hardness in both cases
 - prove NP-hardness for a fixed value of the parameter [Flum, Grohe 1998]
 - Example: k -COLORING

$1|chains(l_{i,j}), p_j = 1, r_j, d_j| \star$ EXACT DELAYS, pathwidth 1

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EXACT DELAYS, pathwidth 1

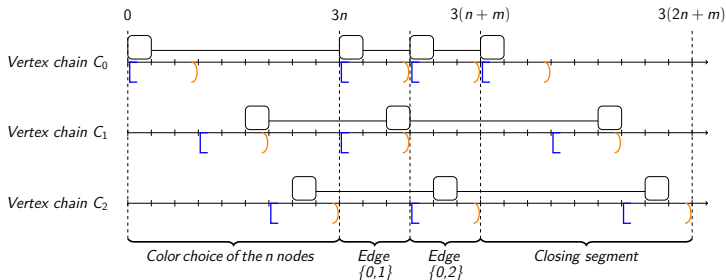
MIN DELAYS, pathwidth 2

MIN DELAYS, pathwidth 1

Conclusion

- Reduction from 3-COLORING: $G = (V, E), n = |V|, m = |E|$

Example: $V = \{0, 1, 2\}, E = (\{0, 1\}, \{0, 2\})$



$1|chains(l_{i,j}), p_j = 1, r_j, d_j| \star$ MIN DELAYS, pathwidth 2

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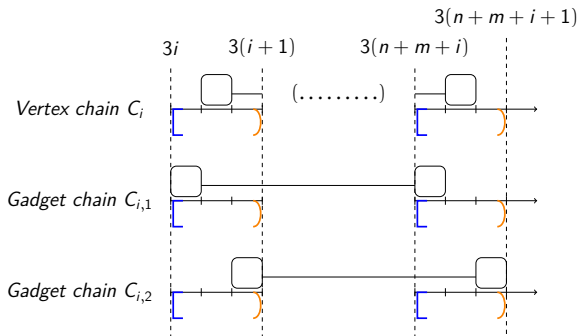
Hardness reduction

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Improvement of MIN DELAYS with pathwidth 1

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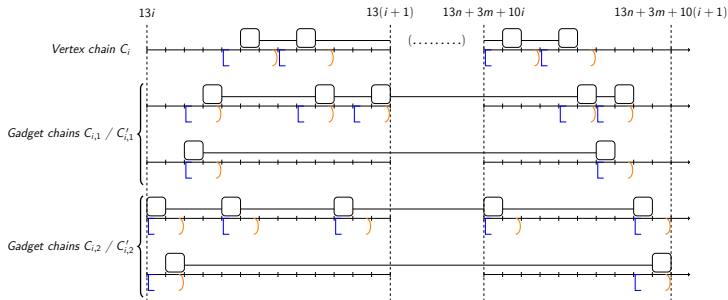
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Theorem

$1|chains(l_{i,j}), p_j = 1, r_j, d_j|*$ is para-NP-complete when parameterized by pathwidth μ in both EXACT DELAYS and MIN DELAYS cases.

More precisely this problem:

- is NP-hard when $\mu \geq 1$,
- can be solved in time $\mathcal{O}(n)$ when $\mu = 0$.

- Further work: investigate maximum delay l_{max}

- FPT with parameter $\mu + l_{max}$?
- hard with parameter l_{max} alone?

Param. complexity of a single machine scheduling problem

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Thank you for your attention!